

DESIGN & CONSTRUCTION
OF A
BOUCHEROT INDUCTION MOTOR

BY
R. L. GRAY
R. HAY

ARMOUR INSTITUTE OF TECHNOLOGY
1911

537.832
G 79



**Illinois Institute
of Technology
Libraries**

AT 219

Gray, R. L.

Design and construction of a
Boucherot Induction Motor

100-100000-100
100-100000-100
100-100000-100
100-100000-100

DESIGN AND CONSTRUCTION OF
A BOUCHEROT INDUCTION MOTOR.

A THESIS

PRESENTED BY

R. L. GRAY and R. HAY.

TO THE

PRESIDENT AND FACULTY

OF

ARMOUR INSTITUTE OF TECHNOLOGY

FOR THE DEGREE OF

BACHELOR OF SCIENCE IN ELECTRICAL ENGINEERING

HAVING COMPLETED THE PRESCRIBED COURSE OF STUDY IN

ELECTRICAL ENGINEERING

ILLINOIS INSTITUTE OF TECHNOLOGY
PAUL V. GALVIN LIBRARY
35 WEST 30RD STREET
CHICAGO, IL 60616

L. C. Morrin
Dean of Cultural Studies

Approved
E. H. Freeman
Prof. of Elect. Eng.
H. M. Raymond
Dean of Eng. Studies

1.832
9

DESIGN & CONSTRUCTION OF A BOUCHEROT INDUCTION MOTOR.

The object of this work is to design a Boucherot rotor to be used in a 10 HP, G.E. 25 Cycle, 80 Volt, 4 Pole, 2-3 Phase Induction Motor.

The only difference between a Boucherot Induction Motor and the ordinary squirrel cage type is in the rotor. Instead of having one squirrel cage, the Boucherot Motor has two or more placed one inside the other. The object of the two squirrel cages is to give the rotor a better starting torque with less current consumption and also to give a better running characteristic.

FIGURE I. shows the method of placing the two sets of windings. The ~~outer~~ winding has a high resistance and relatively low inductance. The inner winding has a low resistance and high inductance due to the greater leakage surface. At the start the frequency of the flux in the rotor equals the stator frequency, hence the high inductance cage will carry practically no current. The outer winding or low inductance winding will furnish the torque, and since the resistance of this winding is high and practically equal to the reactance, we will get maximum torque at the start. Under running conditions the frequency of the flux in the rotor will be proportional to the slip and since the slip is small the frequency will be small and the reactance of the inner winding will be small. The impedance of the inner winding will therefore be small under

DESIGN & CONSTRUCTION OF A BOUNCHNOT
INDUCTION MOTOR.

The object of this work is to design a Bouchnot motor

to be used in a 10 HP, 6.6. 25 Cycle, 80 Volt, 4 Pole, 2-3

Phase Induction Motor.

The only difference between a Bouchnot Induction Motor

and the ordinary squirrel cage type is in the rotor. Instead

of having one squirrel cage, the Bouchnot Motor has two or

more placed one inside the other. The object of the two squirrel

cage is to give the rotor a better starting torque with

less current consumption and also to give a better running

characteristic.

FIGURE 1. shows the method of placing the two sets of

windings. The outer winding has a high resistance and relative-

ly low inductance. The inner winding has a low resistance and

high inductance due to the greater leakage surface. At the

start the frequency of the flux in the rotor equals the stator

frequency, hence the high inductance cage will carry practically

no current. The outer winding or low inductance winding

will furnish the torque, and since the resistance of this wind-

ing is high and practically equal to the resistance, we will

get maximum torque at the start. Under running conditions

the frequency of the flux in the rotor will be proportional

to the slip and since the slip is small the frequency will be

small and the resistance of the inner winding will be small.

The impedance of the inner winding will therefore be small under

Fig 1
Stampings for 10HP Induction Motor
Double Rotor Conductors.



Thickness of Stampings
Scale 6" = 1'

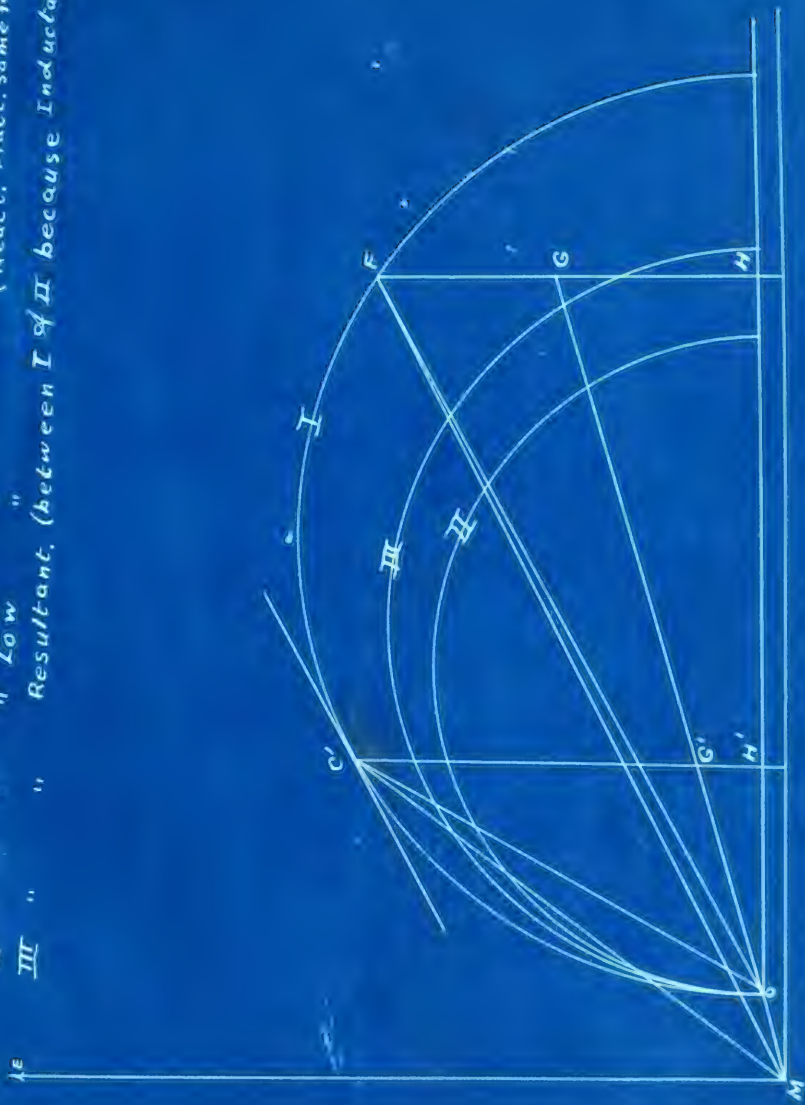
No

I Circle Diagram for present winding & also for high Res Winding

II " " " " Low
(React. pract. same for both)

LOW

" Resultant, (between I & II because Inductances in II)



running conditions and it will furnish the torque or the greater portion of the torque at a minimum slip.

the total characteristic is shown by curve 3, FIG. 2, which is the resultant of curves 1 and 2. Where 1 is the curve for the high resistance winding and 2 is the curve for the low resistance winding.

An idea of the running and starting characteristics of the Boucherot Rotor can also be obtained from the circle diagram of each winding. The inner winding will have a smaller circle than the outer winding, because the reactance of the inner winding is greater. The resultant quantities can be obtained by the vector addition of these two circles, i.e., we would have to know the phase and magnitude of the currents in each one at the same time and by adding them vectorially we would obtain the resultant circle diagram. The diameter of the resultant circle would be equal to

$$\frac{E}{X_1 + X_2}$$

Where E - impressed E M F of primary

X_1 - primary reactance

X_2 - secondary " reduced to primary reactance.

X_2 is the resultant reactance of the two winding. The windings may be considered as in parallel because the current in any winding is proportional to the impedance of that winding. The easiest way to find the impedance of the two windings would be to find the admittance and take the reciprocal as the impedance.

It will be seen that it will be the torque of the

torque of the torque of a minimum size.

The torque of the torque is shown by curve 2, Fig. 2,

of curves 1 and 2.

For the two winding winding and 2 in the curve for the low

resistance winding.

In the case of the winding and winding characteristics

of the winding can also be obtained from the curve

of each winding. The inner winding will have a smaller

than the outer winding, because the resistance of the in

The resultant characteristic can be obtained

of the winding and the winding.

and by adding them vectorially we would

The resultant circle diagram. The diameter of the re-

sultant circle would be equal to



expressed as $\frac{1}{2} \sqrt{1 - \frac{R^2}{Z^2}}$ of primary

secondary

referred to primary resistance.

in the resultant resistance of the two windings. The winding

may be considered as in parallel because the current in any wind-

ing is proportional to the resistance of that winding. The resultant

resistance of the winding is the sum of the resistances of the

two windings and the resistance of the winding.

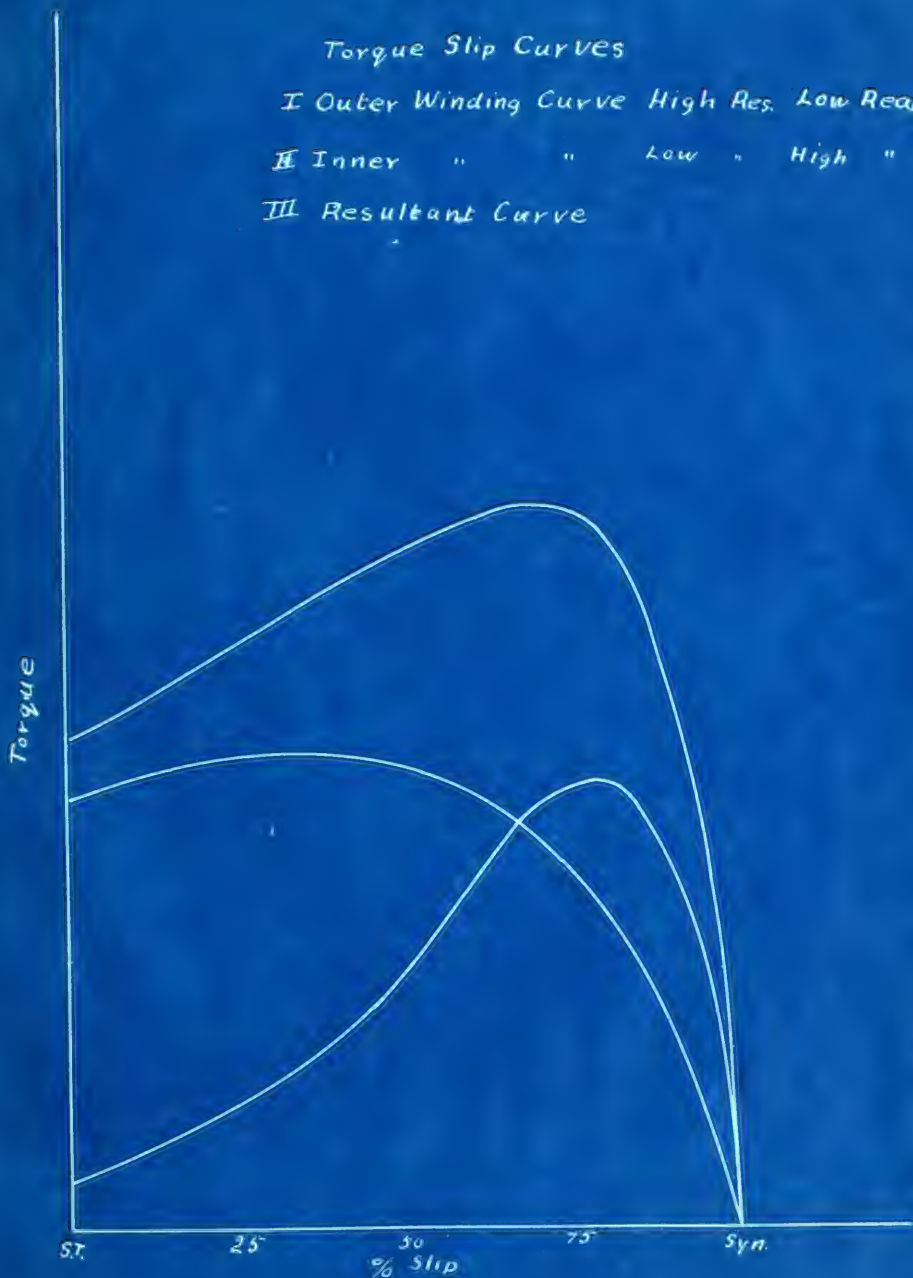
Fig 2

Torque Slip Curves

I Outer Winding Curve High Res. Low Reac.

II Inner " " Low " High "

III Resultant Curve



In designing the rotor our object was to obtain a maximum torque at starting and minimum slip at normal full load. This being our object we found it would be easier to obtain the component circles first and then determine the resultant circle diagram.

The present study was designed to investigate the effects of the use of a computer-based system on the performance of a task. The results of the study showed that the use of the system significantly improved the performance of the task. The study was conducted in a laboratory setting and involved a group of participants who were trained in the use of the system. The results of the study were compared to a control group that did not use the system. The results showed that the use of the system significantly improved the performance of the task, as measured by the time taken to complete the task and the number of errors made. The study also found that the use of the system reduced the cognitive load on the participants, as measured by the number of errors made. The results of the study suggest that the use of a computer-based system can improve the performance of a task and reduce the cognitive load on the user.

Calculations

Motor running No Load. 25 Cycles. $\sqrt{3} \phi$.

$$E = 80 \text{ Volts}$$

$$I_{pe} = 32.8 \text{ Amps. Exciting Current.}$$

$$W_1 = -1000 \quad W_2 = 1700 \quad \text{Exciting Loss} = 700 \text{ W.}$$

Rotor Blocked. 25 ~

$$E = 14.5 \text{ Volts} \quad R_p = .0647 \Omega \text{ D.C.}$$

$$I_p = 95 \text{ Amps}$$

$$W_1 = 1350. \quad W_2 = 450 \quad W = 1800$$

Cal. for Circle Diagram (Equivalent single ϕ .)

$$I_{peq} = \sqrt{3} I_{pe} = \sqrt{3} \times 32.8 = 57 \text{ A.}$$

$$\cos \phi = \frac{700}{\sqrt{3} \times 80 \times 32.8} = .1536. \phi = 81^\circ 50'$$

Rotor Blocked 80 V. Eq. single ϕ I.

Assume $I \propto E$

$$\frac{I}{80} = \frac{95}{14.5} \quad I = 524$$

$$I_{eq} = \sqrt{3} \times 524. = 910 \text{ Amp.}$$

$$\cos \phi = \frac{1800}{\sqrt{3} \times 14.5 \times 95} = .754. \phi = 41^\circ$$

Primary Copper Loss at 80 v.

$$= \frac{3}{2} I^2 R = \frac{3}{2} \times 524^2 \times .0647. = 26700 \text{ W.}$$

$$\frac{26700}{80} = 334. \text{ Amp.}$$

$$I_{eq} \text{ at 10 H.P.} = \frac{7460}{80} = 93.4 \text{ Amp.}$$

High Res. Winding.

From Diagram.

C' is point PT of tangency of a line || to OG.

$$\frac{R_{sk}}{R_p} = \frac{G'C'}{G'H'} = \frac{11.52 \times .03235}{5.98} = R_{sk}$$

$$R_{sk} = .0622 \quad R_p = E_{\phi} \text{ Single } \phi \text{ Res} = \frac{1}{2} \times .0647$$

R_{sk} is the Res. that \times by the sec. current gives the sec. copper loss

R_{sk} the effect. res. is \propto to the calculated res.

$R_{sk} = k$ Recalculated from size \times length of conductors.

Res. of winding of present rotor is also \propto to its calculated Res. i.e. $R_{pres} = k R'_{calculated}$

R_{pres} from diagram = .0338 Effective.

$R' = \text{Res. of conds.} + \text{Res. of Ring.}$

Res. of each conductor. = $\frac{k'L}{A}$

$$= .0000084833 \frac{\frac{72}{.35 \times .6}}{A}$$

$$= .0000283 \omega$$

Since there are 4 poles there will be 4

paths in ||. Current in rotor varies from a max. under the pole to zero midway between poles. (a dist. of 90 electrical degrees). This is equivalent to a res R_x varying from $\frac{R}{2}$ to infinity. $\therefore R_x = R \frac{1}{\cos x}$

$$R = .0000283 \omega$$

$$R_x = .0000283 \cdot \frac{1}{\cos x}$$

Since there are 47 cond. the dist. between each conductor = $\frac{720}{47} = 15.3^\circ$

For 15.3° there are 6 conductors approx.



Res. of conductors $\square = R_c$

$$\frac{1}{R_c} = \frac{1}{R_1} + \frac{1}{R_2} + \frac{1}{R_3} + \frac{1}{R_4} + \frac{1}{R_5} + \frac{1}{R_6}$$

$$R_1 = .0000283 \Omega$$

$$R_2 = \frac{1}{\cos 15.3} \times .0000283 = .0000294$$

$$R_3 = \frac{1}{\cos 30.6} \times .0000283 = .0000328$$

$$R_4 = \frac{1}{\cos 45.9} \times .0000283 = .0000407$$

$$R_5 = \frac{1}{\cos 61.2} \times .0000283 = .0000588$$

$$R_6 = \frac{1}{\cos 76.5} \times .0000283 = .0001215$$

$$R_c = .0000674$$

Since there two cond. per. ϕ .

$$\text{Total } R_c = 2 \times .0000674 = .0001348 \Omega$$

Res. of present rings. $= R_r$

$$R_r = R_1 + R_2 + R_3 + R_4 + R_5 + R_6$$

$R_1 + \dots + R_6 = \text{res. of elementary element between cond.}$

$$R_1 = \frac{kL}{A} = .000000483 \times \frac{.862}{.795} = .000000765 \Omega$$

$$R_2 = \frac{1}{\cos 22.95} \times .000000765 = .00000083$$

$$R_3 = \frac{1}{\cos 38.25} \times .000000765 = .000000974$$

$$R_4 = \frac{1}{\cos 53.55} \times .000000765 = .000001285$$

$$R_5 = \frac{1}{\cos 68.85} \times .000000765 = .00000211$$

$$R_6 = \frac{1}{\cos 84.15} \times .000000765 = .0000075$$

$$R_r = .000011354$$

$$\text{Total } R_r = 2 \times .000011354 = .000022708 \Omega$$

$$R' = 0.00022708 + 0.0001348 = 0.00036188 \Omega$$

This is the calculated Res. of $\frac{1}{4}$ of the rotor,
or between poles.

$$R_{pres} = k R'$$

$$.0338 = k \cdot 0.00036188$$

$$k = 935$$

Cal. res. of high res. Winding = R'_{sh}

$$R'_{sh} \text{ eff.} = .0622$$

$$R'_{sh} = \frac{.0622}{935} = .0000665 \Omega$$

= res. of conds. + res of ring.

Assume diam. of cond. = .4"

by similar calculations as above the res. of con
= .0000224

$$\text{res. of rings} = 0.000665 - 0.000224 = .000441 \Omega$$

$$0.000441 = \frac{kL}{A} \quad kL = 0.00018804$$

$$\text{For copper } A = .449 \text{ sq. in.}$$

$$\text{for iron } 5.44 \times .449 = 2.45 \text{ sq. in.}$$

$$\text{for one ring } A = \frac{2.45}{2} = 1.225 \text{ sq. in.}$$

Low res. Winding.

Assume 2% slip. Eff. res. from geometr
of circle diagram = .01495

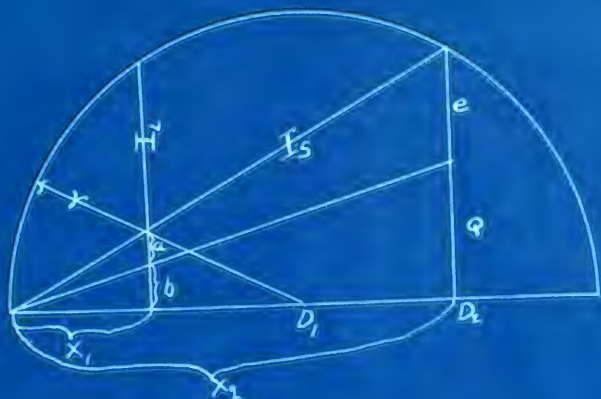
$$\text{Cal. } R = \frac{.01495}{935} = .000016$$

Assume diam of cond = $\frac{1}{2}$ "

By similar calculations as before.

$$A = 2.575 \text{ sq. in. Copper.}$$





Reactance Calculations.

Calculations for inner winding diameter of circle diagram.

$$\text{Assume slip} = 2\% = \frac{a}{I_2 + a} = \frac{a}{98.4 + a}$$

$$a = 1.905 \text{ amp.}$$

$$R_p = .0325 \quad R_s = .01495 \text{ assumed.}$$

$$R_s^H = .0622$$

$$\frac{a}{b} = \frac{e}{Q} = \frac{R_s}{R_p} = \frac{.01495}{.03235} = .464$$

$$I_s^2 R_s = 280$$

$$I_s^2 = \frac{280}{.01495} e = 5355 e$$

$$I_s^2 = (e + Q)^2 + X_2^2$$

$$5355 e = (e + Q)^2 + X_2^2$$

$$e = .464 Q$$

$$\therefore \text{subst. } 2480 Q = (.464 Q + Q)^2 + X_2^2$$

$$X_2^2 = 2480 Q - 2.146 Q^2$$

$$(X_1 - r)^2 + (I_2 + a + b) = r^2$$



$$\frac{a}{b} = .464$$

$$\therefore b = \frac{1.905}{.464} = 4.1$$

$$(X_1 - r)^2 + (93.4 + 1.905 + 4.1)^2 = r^2$$

$$(1) X_1^2 - 2X_1 r + 9900 = 0$$

$$(X_2 - r)^2 + (e + Q)^2 = r^2$$

$$X_2^2 - 2rX_2 + (.464Q + Q)^2 = 0$$

$$(2) X_2^2 - 2rX_2 + 2.146Q^2 = 0$$

Value of r from (1)

$$r = \frac{9900 + X_1^2}{2X_1}$$

$$\text{Now } \frac{a+b}{e+Q} = \frac{X_1}{X_2} \text{ or } X_1 = \frac{1.905 + 4.1X_2}{1.464Q}$$

$$= 4.1 \frac{X_2}{Q}$$

$$\frac{X_2}{X_1} = \frac{Q}{4.1}$$

sub in (2)

$$2480Q - 2.146Q^2 - \frac{2X_2(9900 + X_1^2)}{2X_1} + 2.146Q^2 = 0$$

$$2480Q - \frac{Q}{4.1} \left\{ 9900 + \frac{4.1^2}{Q^2} (2480Q - 2.146Q^2) \right\} = 0$$

$$2480Q - 2410Q - 10200 + 8.8Q = 0$$

$$78.8Q = 10200$$

$$Q = 129.5$$

Solve 2 for

$$2480 \times 129.5 - 2 \times 535r = 0$$

$$r = \frac{322000}{1070} = 301 \text{ amp.}$$

$$\text{diameter of circle} = 2 \times 301 = 602$$

total reactance of primary & low res.

$$\text{secondary.} = \frac{80}{602} = .1335 \omega$$

Reactance of present winding & also of high winding. = $\frac{80}{1370} = .0584 \omega$



reactance of low winding

$$= .1335 - .0584 = .0751 = \text{reactance of holes \& slots}$$

$$\begin{aligned} \text{reactance of the holes} &= 2 C f L_s n_1^2 \frac{N_1^2 P_1'}{N_2 P_2'} (.625) 10^{-7} \\ &= 2 \times .75 \times 25 \times 5 \times 62 \frac{24 \times 3}{4 \times 11.75} (.625) 10^{-7} = .0155 \\ &= \text{react per } \phi \end{aligned}$$

Now .0751 is the eq. single ϕ reactance & must be reduced to 3 ϕ quantity by mult. by $\frac{3}{2}$

$$X_{\text{per } \phi} = \frac{3}{2} \times .0751 = .1130$$

Reactance of the slot

$$= .1130 - .0155 = .098$$

$$.098 = 24800 \times \frac{b}{a} \times 10^{-7}$$

$$\frac{b}{a} = 3.95$$

Calculations of reactances

of separate parts $\frac{b}{a} = 3.35$

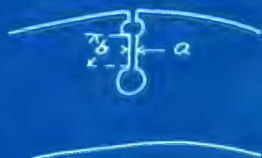
Assume $a = \frac{3}{16}$ "

$$b = .627"$$

Since reactance per $\phi = X = .098$

$$= 2 C f L_s n_1^2 \frac{N_1^2 b_1'}{N_2 b_2'} \times \frac{b}{a} 10^{-7}$$

$$= 2 \times .75 \times 25 \times 5 \times 62 \times \frac{24 \times 3}{4 \times 11.75} \times \frac{b}{a} 10^{-7} = 24800 \frac{b}{a} \times 10^{-7}$$



C O N S T R U C T I O N

Owing to the peculiar form of the stamping that would be required to make up the laminated core of this rotor, it was found necessary to form them by another method than stamping. For this reason and the difficulty entailed in cutting and fitting the laminations, it was decided to do without a spider and fit the laminations directly on the shaft.

The laminations were cut from sheet iron and placed on a specially made arbor with a shoulder on one end and a thread on the other. In order to drill the hole in the laminations to fit on the arbor, a special drill the required size had to be made. Two cast iron flanges, FIG. 4, were made to fit the arbor and the laminations screwed up between them, placed in a lathe and turned down to size.

Before putting the laminations on the arbor one flange was laid off and holes drilled $1/16$ " larger than the conductors as in Fig. 1. This was used as guide in drilling the holes in the laminations. For this drilling extra long drills had to be obtained. After drilling the work was placed in a milling machine and slots cut. It was then taken apart, the laminations cleaned up and placed on the shaft made similar to the one in Fig. 3, with the exception that a thread was cut on one end. One flange was fastened in position with set screws and the laminations tightened up on the shaft.

The flanges were cut off to allow the end rings Fig. 5, to be placed in position. The copper bars were cut to allow a projection of $1-1/4$ " on either side. The $1/2$ " bars were cut down to $3/8$ " diameter for this distance of $1-1/4$ ".

DESCRIPTION OF THE APPARATUS

...ing to the peculiar form of the stamping that would
be required to make up the laminated core of this motor, it
was found necessary to form them by another method than stamp-
ing. This reason and the difficulty entailed in casting
and fitting the laminations, it was decided to do without a
press and fit the laminations directly on the shaft.
The laminations were cut from sheet iron and placed
on a specially made arbor with a shoulder on one end and a
flange on the other. In order to drill the holes in the lami-
nations to fit on the arbor, a special drill the required size was
made. Two cast iron flanges, 1 1/2" in diameter, were made to fit
the arbor and the laminations were placed between them, placed
in a lathe and turned down to size.
Before putting the laminations on the arbor one flange
was laid off and holes drilled 1/16" larger than the conductors
as in fig. 1. This was used as guide in drilling the holes in
the laminations. On this drilling extra long drills had to be
used. After drilling the holes in the laminations they were
put on the arbor and the shaft made similar to the one in fig. 2.
With the exception that a thread was cut on one end. One flange
was fastened in position and the other was turned up on the shaft.
The flanges were cut off to allow the end rings fig. 3,
to be placed in position. The copper bars were cut to allow a
separation of 1/4" on either side. The 1/4" bars were cut

Induction Motor Shaft

Scale 4" = 1'

Fig. 3.



Key.

Fig 4

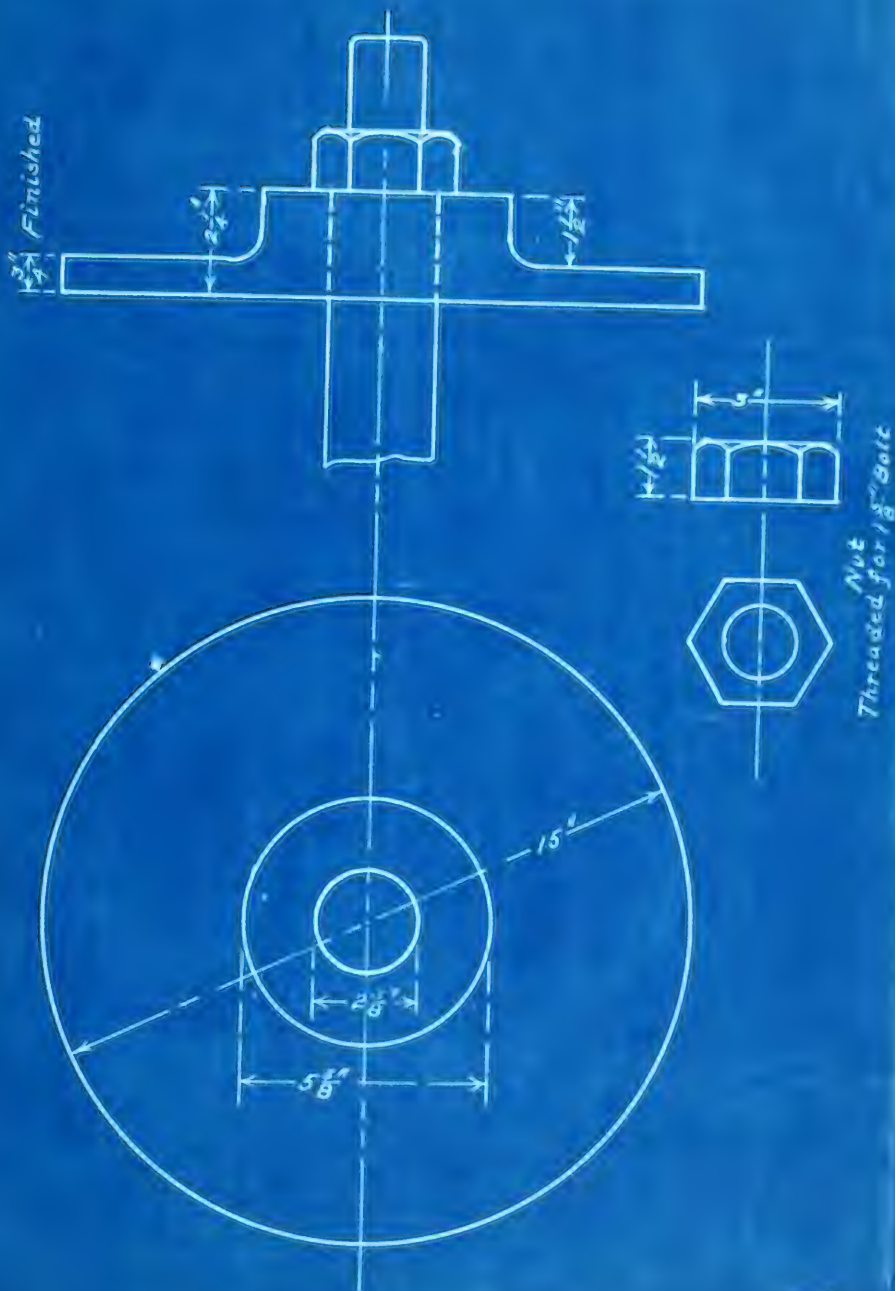
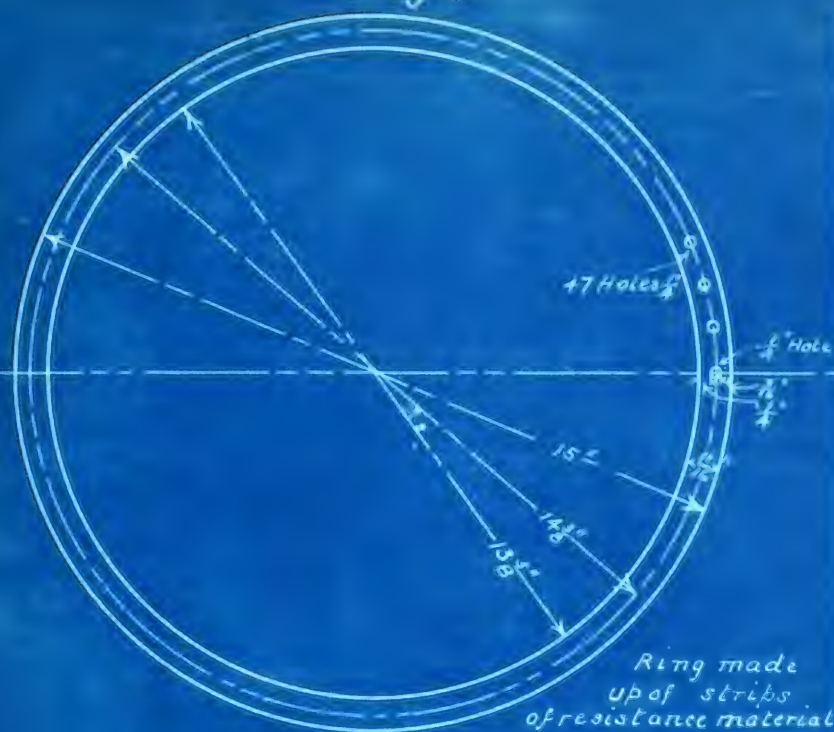


Fig 5



Ordinary paper was used for insulation. The end rings, the inner one of brass to provide a low resistance, and the outer of cast iron for the high resistance, were fastened on with brass nuts. The completed rotor was then filed to exact size and placed in the stator where it ran satisfactorily.

Due to the fixed dimensions of the rotor it was necessary to change the calculated values to the values shown on the blue prints.

After the completion of the new rotor we ran a test on it to obtain the exciting and rotor blocked current, (which is a measure of the instantaneous starting current.

Data obtained for new rotor.

Motor running no load. - Exciting current.

$E = 80$, $I = 23.5/10$, average

$W_1 = 1300$ $W_2 = 340$, $W = 960$ watts.

Rotor blocked

$E = 25$, $I = 72.5$ average

$W_1 = 1650$, $W_2 = 200$, $W = 1850$ watts.

As seen from the data the exciting current is much smaller for the new rotor than the old: this is probably due to the smaller iron loss and slightly less air gap. The power consumed is greater, but this might be due to the newness of the moving parts.

The rotor blocked quantities are about 50% smaller for the new rotor than for the old.

indicated that the rotor was not in the correct position. The rotor was then moved to the correct position and the test was repeated. The rotor was then moved to the correct position and the test was repeated. The rotor was then moved to the correct position and the test was repeated.

The rotor was then moved to the correct position and the test was repeated. The rotor was then moved to the correct position and the test was repeated. The rotor was then moved to the correct position and the test was repeated.

After the completion of the test, the rotor was then moved to the correct position and the test was repeated. The rotor was then moved to the correct position and the test was repeated. The rotor was then moved to the correct position and the test was repeated.

After the completion of the test, the rotor was then moved to the correct position and the test was repeated. The rotor was then moved to the correct position and the test was repeated. The rotor was then moved to the correct position and the test was repeated.

After the completion of the test, the rotor was then moved to the correct position and the test was repeated. The rotor was then moved to the correct position and the test was repeated. The rotor was then moved to the correct position and the test was repeated.

After the completion of the test, the rotor was then moved to the correct position and the test was repeated. The rotor was then moved to the correct position and the test was repeated. The rotor was then moved to the correct position and the test was repeated.

After the completion of the test, the rotor was then moved to the correct position and the test was repeated. The rotor was then moved to the correct position and the test was repeated. The rotor was then moved to the correct position and the test was repeated.

